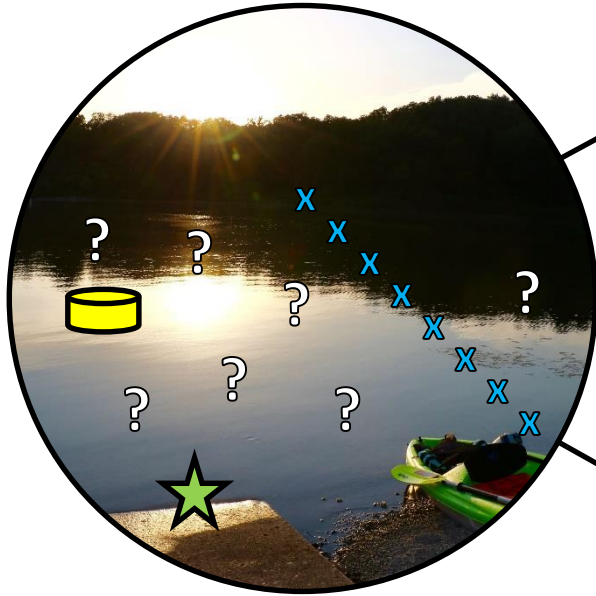


What's in a lake? An overview of cutting-edge lake survey technologies

Jess Z. LeRoy and Rick Huizinga
Central Midwest Water Science Center (IL, IA, MO)
U.S. Geological Survey

water quality
water supply turbidity
drinking water weeds
sedimentation
irrigation swimming management
energy ecology
algae **LAKES** toxins watershed
bacteria flood control fishing
infrastructure
ecosystems
boating recreation
capacity
invasive species

What do we want to know?



QUALITY

- Temperature
- Turbidity/suspended sediment
- pH/alkalinity
- Dissolved oxygen
- Bacteria
- Algae
- Nutrients
- Specific conductance
- Etc.

QUANTITY

- Water level
- Bathymetric maps
- Lake capacity (surface area – capacity tables)
- Sedimentation or erosion rates

How can we fill the gaps between
gages/buoys/samples?

How can we get at water **quantity**?

Mapping bathymetry and water quality in lakes

A mapping approach fills **SPACE**
with data in three-dimensions



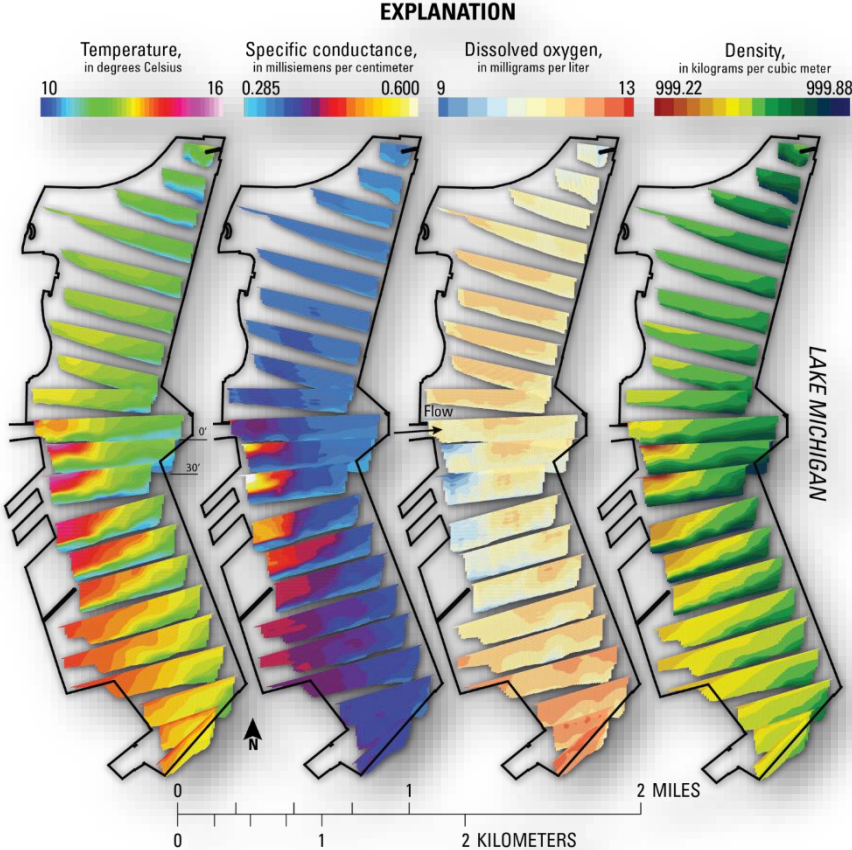
Mapping bathymetry and water quality in lakes

A mapping approach fills **SPACE** with data in three-dimensions

- ✓ QUANTIFY
- ✓ VISUALIZE
- ✓ CONNECT



UNDERLYING PROCESSES



What can we measure?

Hydroacoustics



WATER

SOUND

Bathymetry: single-beam echosounder, multi-beam echosounder (MBES)

Velocity: acoustic doppler current profiler (ADCP)

Water quality sensors

Temperature
Specific conductance
pH
Turbidity
Dissolved oxygen
Chlorophyll
Blue-green algae



Integrated with GPS





Mapping bathymetry and water quality in lakes

spatially dense, georeferenced data
is needed for mapping bathymetry
and water quality

It helps to be mobile!



Manned Boat

(boat-mounted and towed
instruments)



RC Boat



Autonomous Underwater Vehicles (AUV)



Bathymetry



Bathymetry

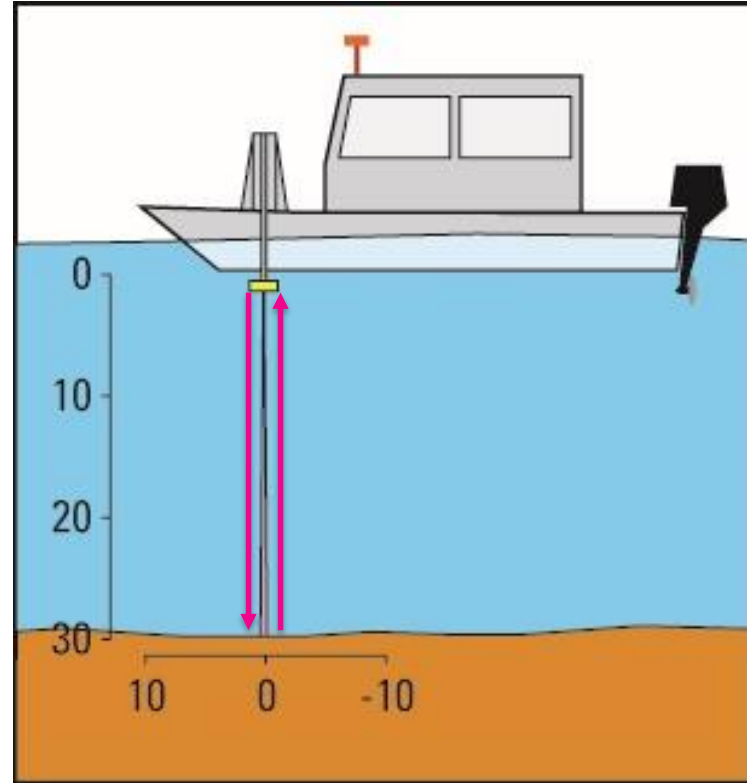
Echosounders measure depth by timing how long it takes for a “beam” of sound to travel from the instrument to the bed and back

$$\text{speed} = \frac{\text{distance}}{\text{time}}$$

$$\text{speed of sound in water} = \frac{2 \times \text{depth}}{\text{time elapsed}}$$

known

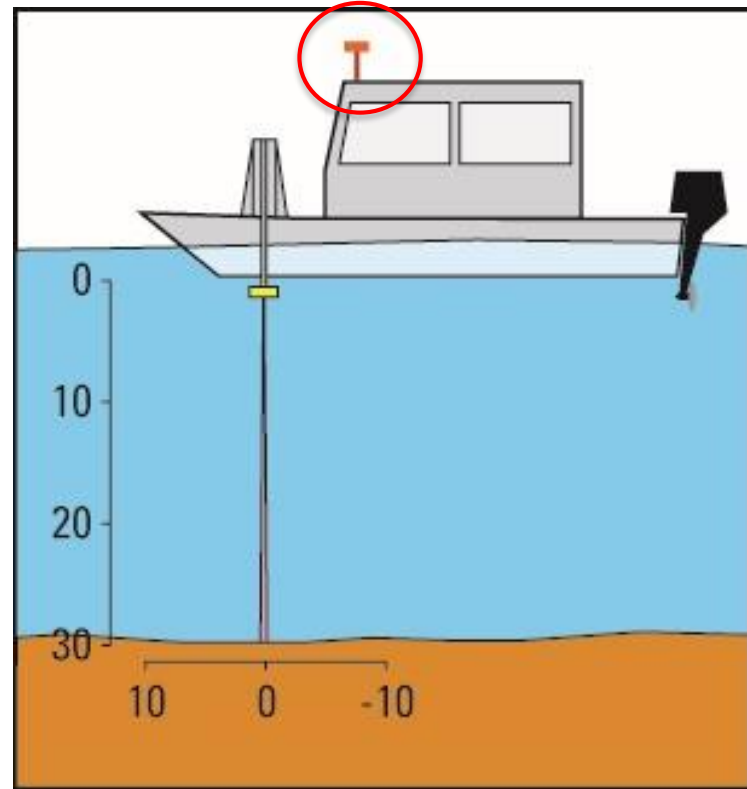
measured



Bathymetry

GPS data allows the measured depths to be mapped in space

If the vertical accuracy of the GPS is good enough, the depths can also be converted to bed elevations



Bathymetry

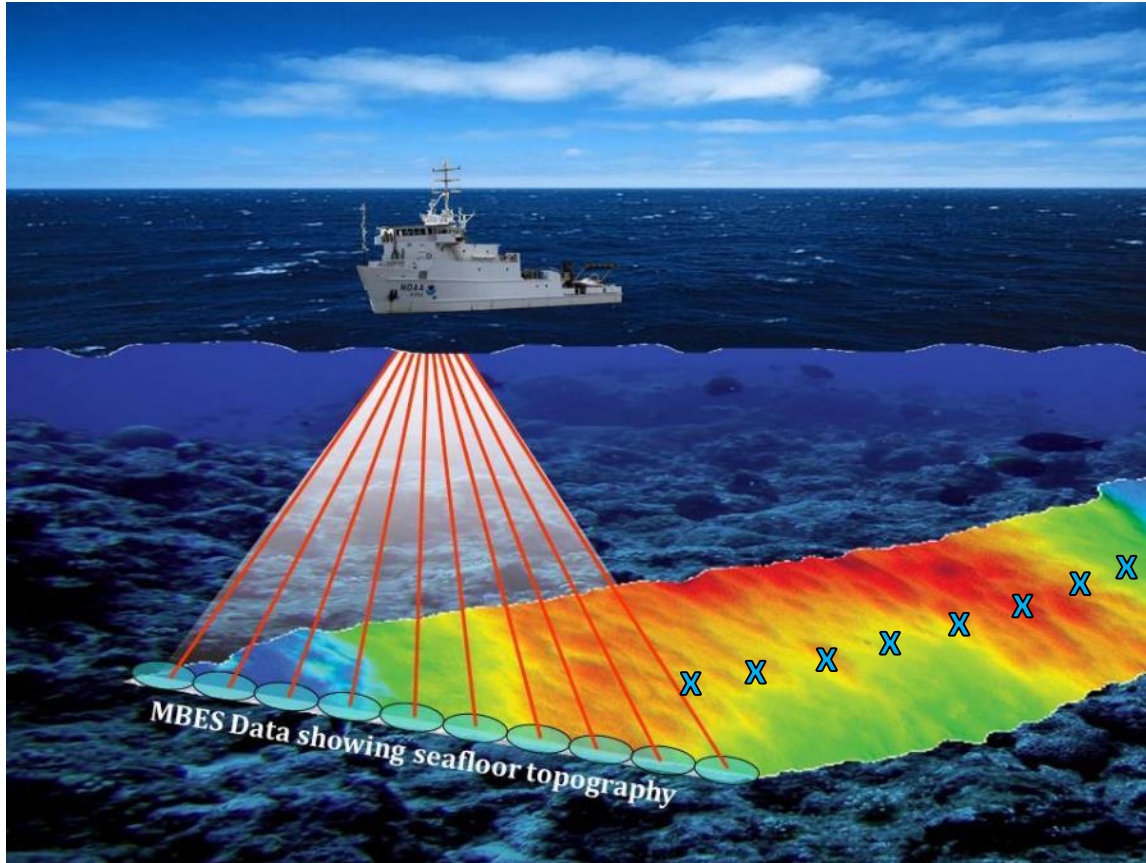
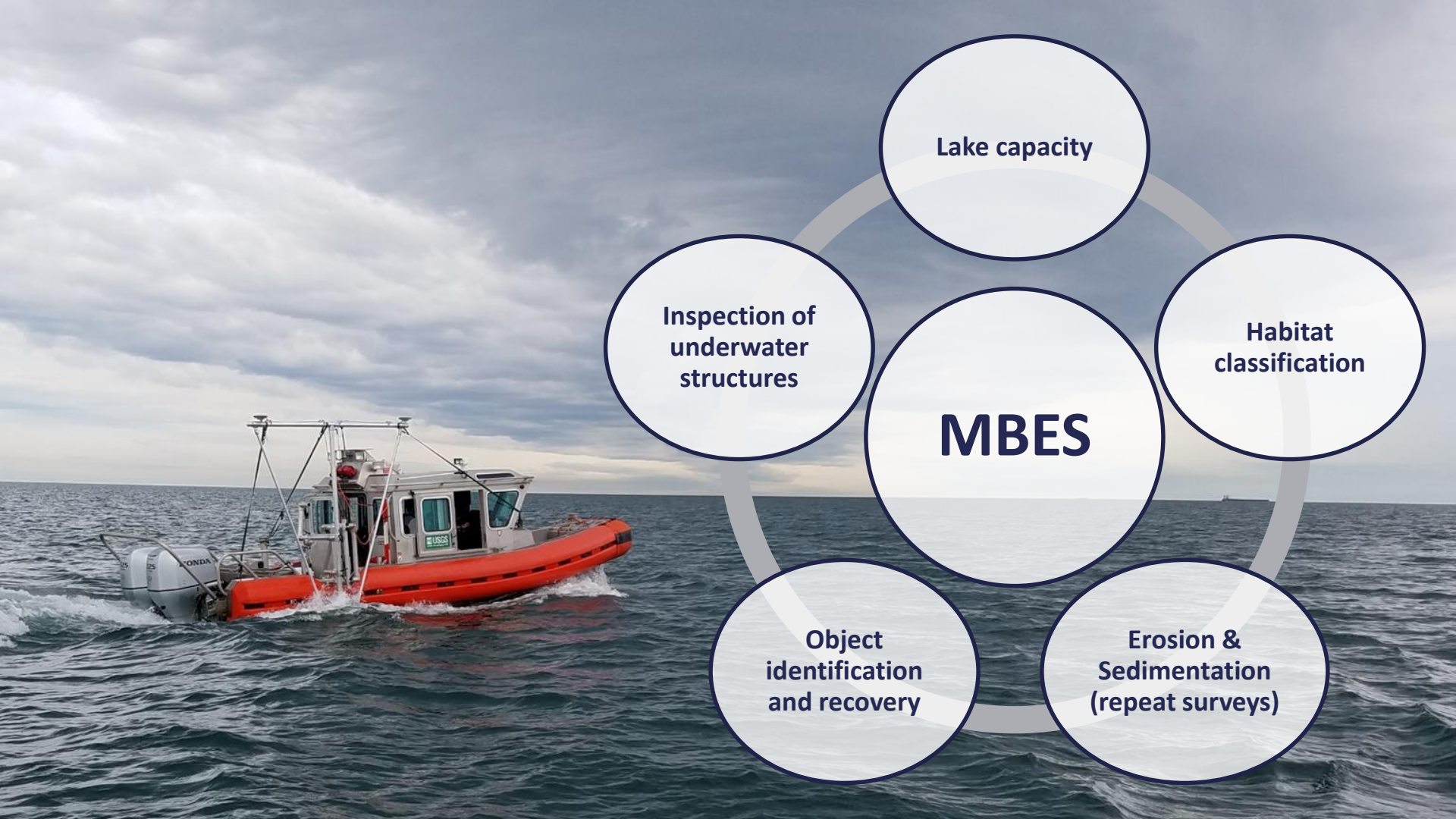


Image from NOAA Photo Library

Single-beam: point
Multi-beam (MBES): “swath”

MBES are integrated with a dual antenna GPS system AND a motion sensor...high resolution and high accuracy bathymetry



Lake capacity

**Inspection of
underwater
structures**

**Habitat
classification**

MBES

**Object
identification
and recovery**

**Erosion &
Sedimentation
(repeat surveys)**

Bathymetry → Surface Area – Capacity Table

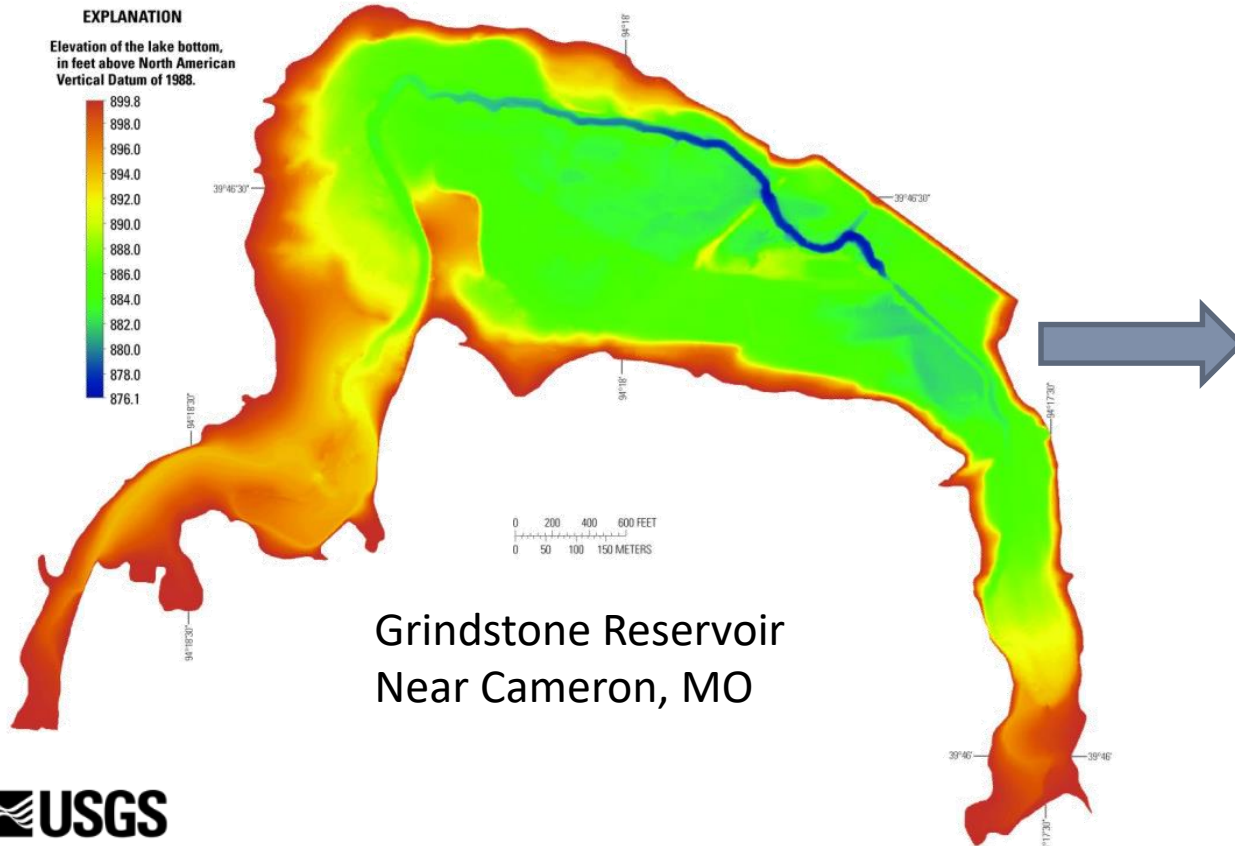


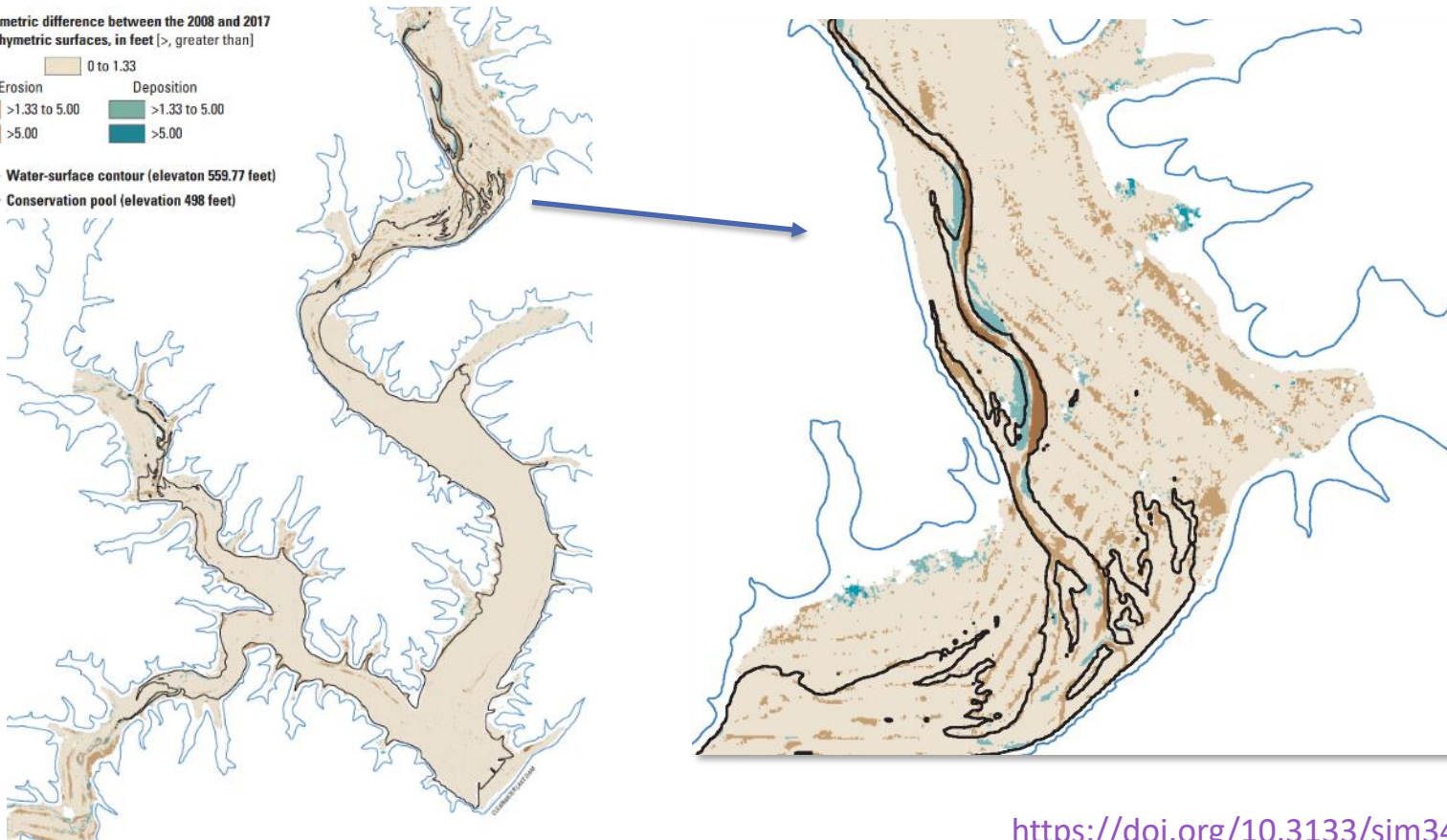
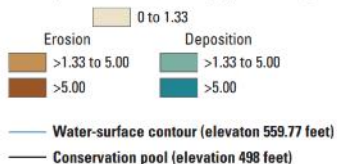
Table 7. Area and capacity at specified elevations for Grindstone Reservoir near Cameron, Missouri, on July 2, 2013.

[The average water-surface elevation during the survey was 900.4 feet above the North American Vertical Datum of 1988; volumes calculated from bathymetric surface with mean total propagated uncertainty of 0.51 feet]

Elevation, in feet	Area, in acres	Capacity, in acre-feet
878.0	1.38	1.10
880.0	2.66	5.01
882.0	8.61	13.8
884.0	41.3	58.0
886.0	74.0	175
888.0	90.8	342
890.0	107	540
892.0	119	766
894.0	134	1,020
896.0	155	1,310
898.0	175	1,640
899.8	196	1,960

Bathymetry → Erosion/Sedimentation

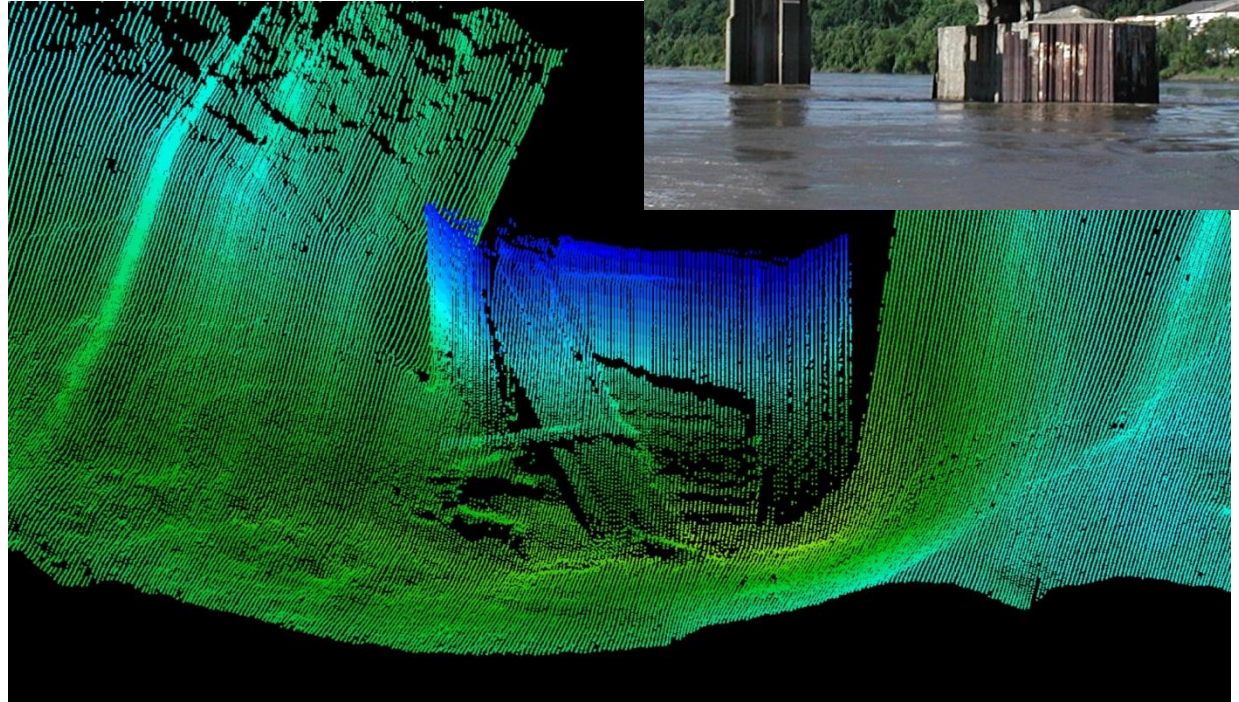
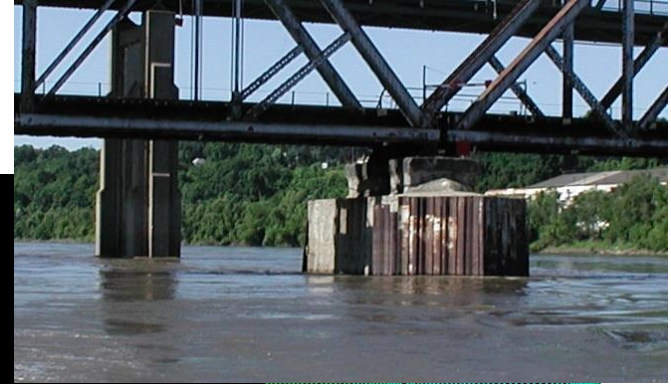
Bathymetric difference between the 2008 and 2017 bathymetric surfaces, in feet (>, greater than)



Bathymetry → Inspection of underwater structures

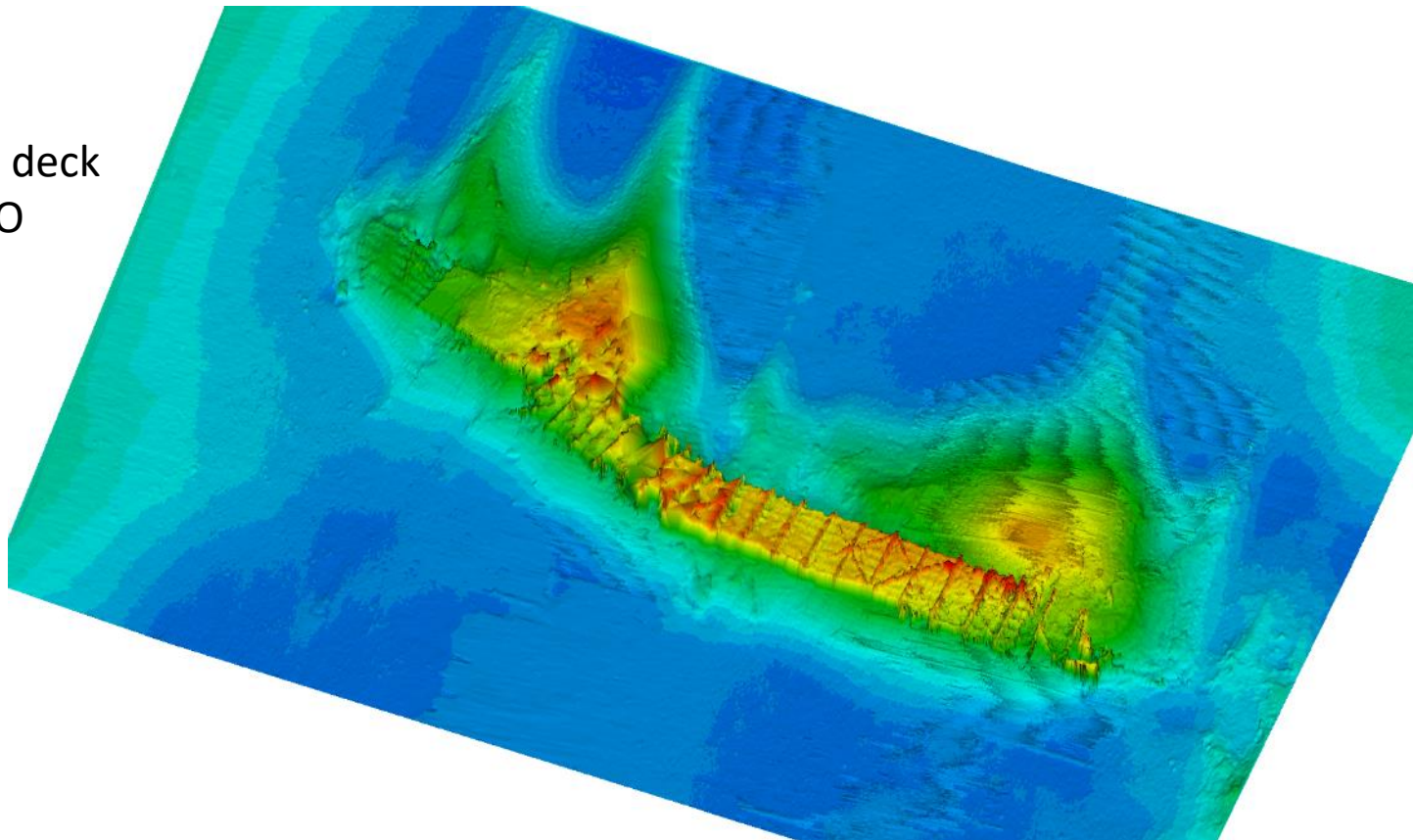
Missouri River at
Atchison, Kansas

Oblique view of U.S.
Railroad bridge

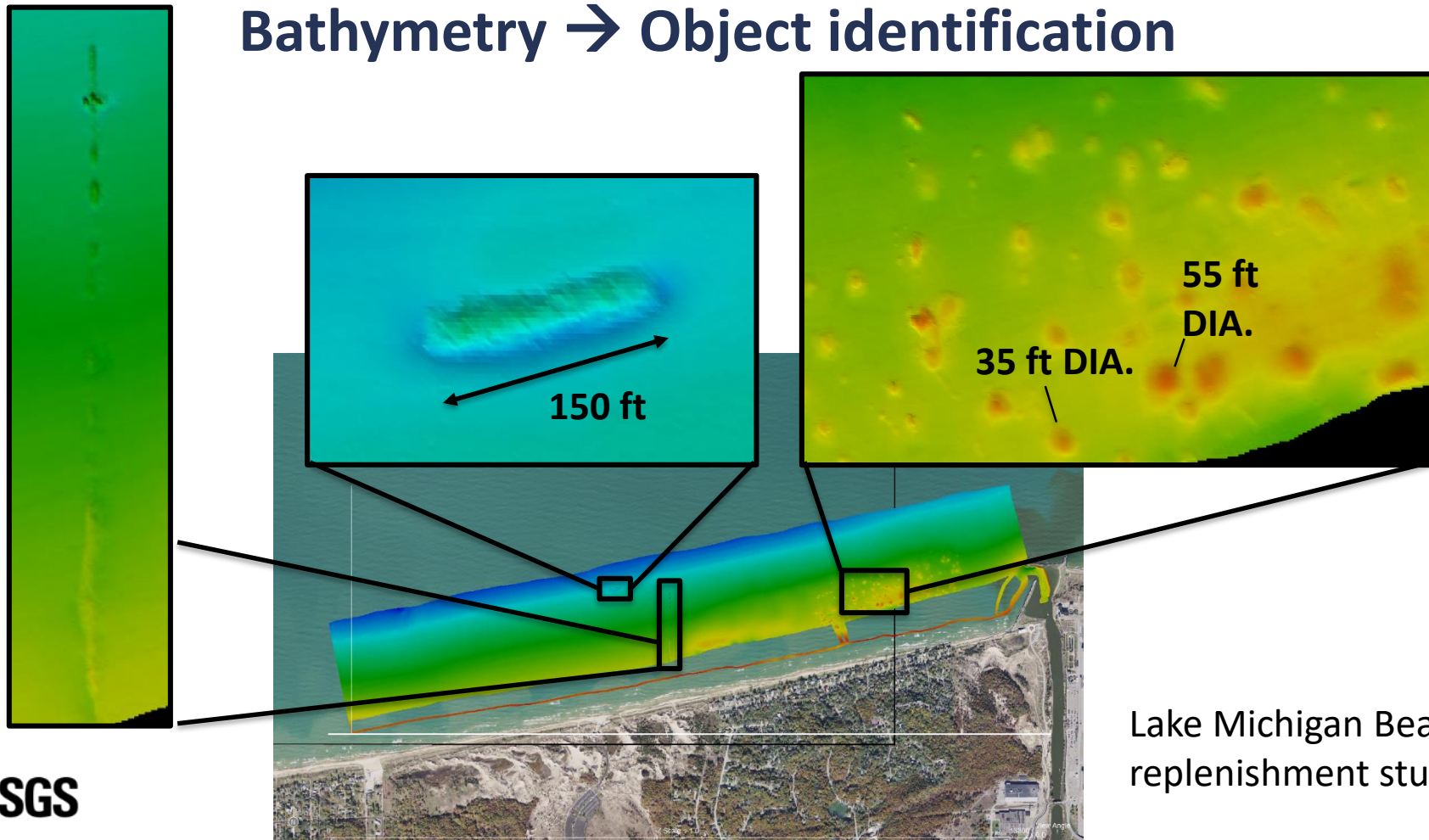


Bathymetry → Object identification

Old fallen bridge deck
near Warsaw, MO

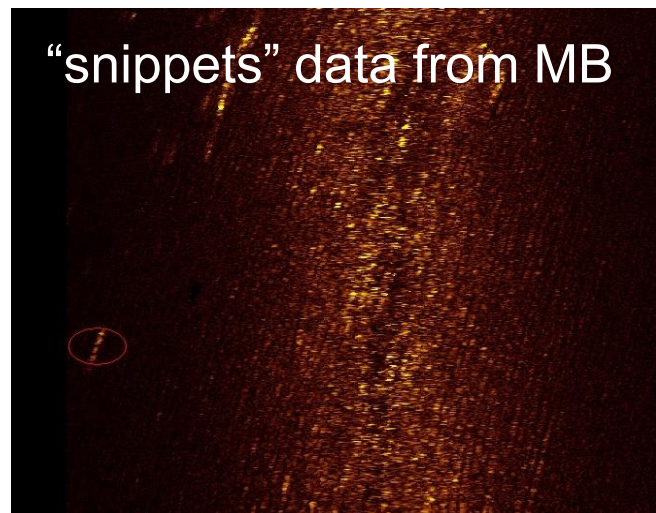
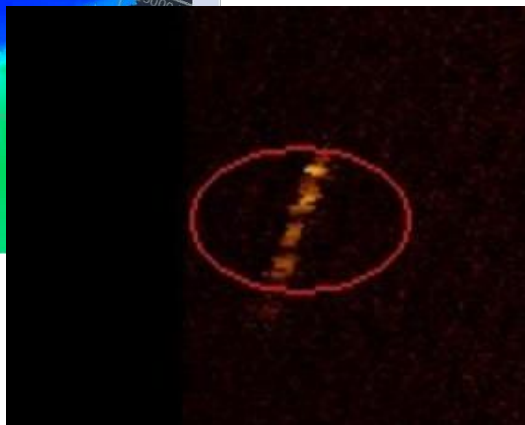
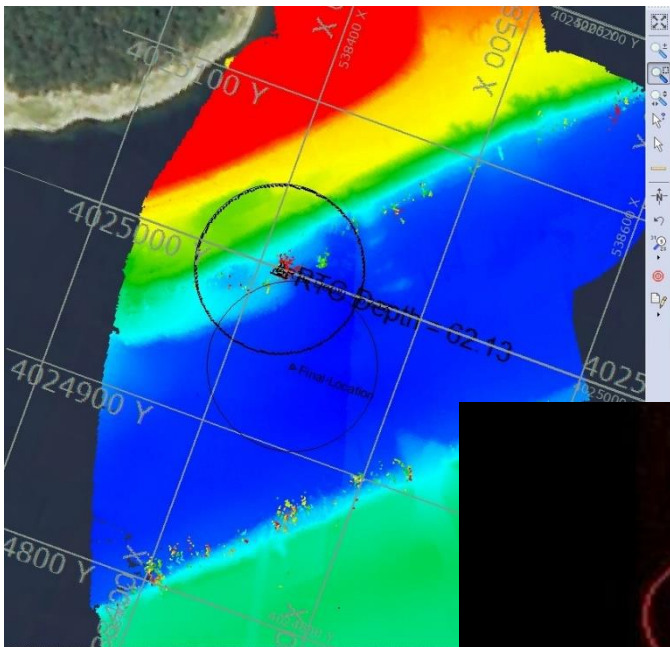


Bathymetry → Object identification



Lake Michigan Beach replenishment study

Bathymetry → Object identification (and side-scan)



MBES Tradeoffs

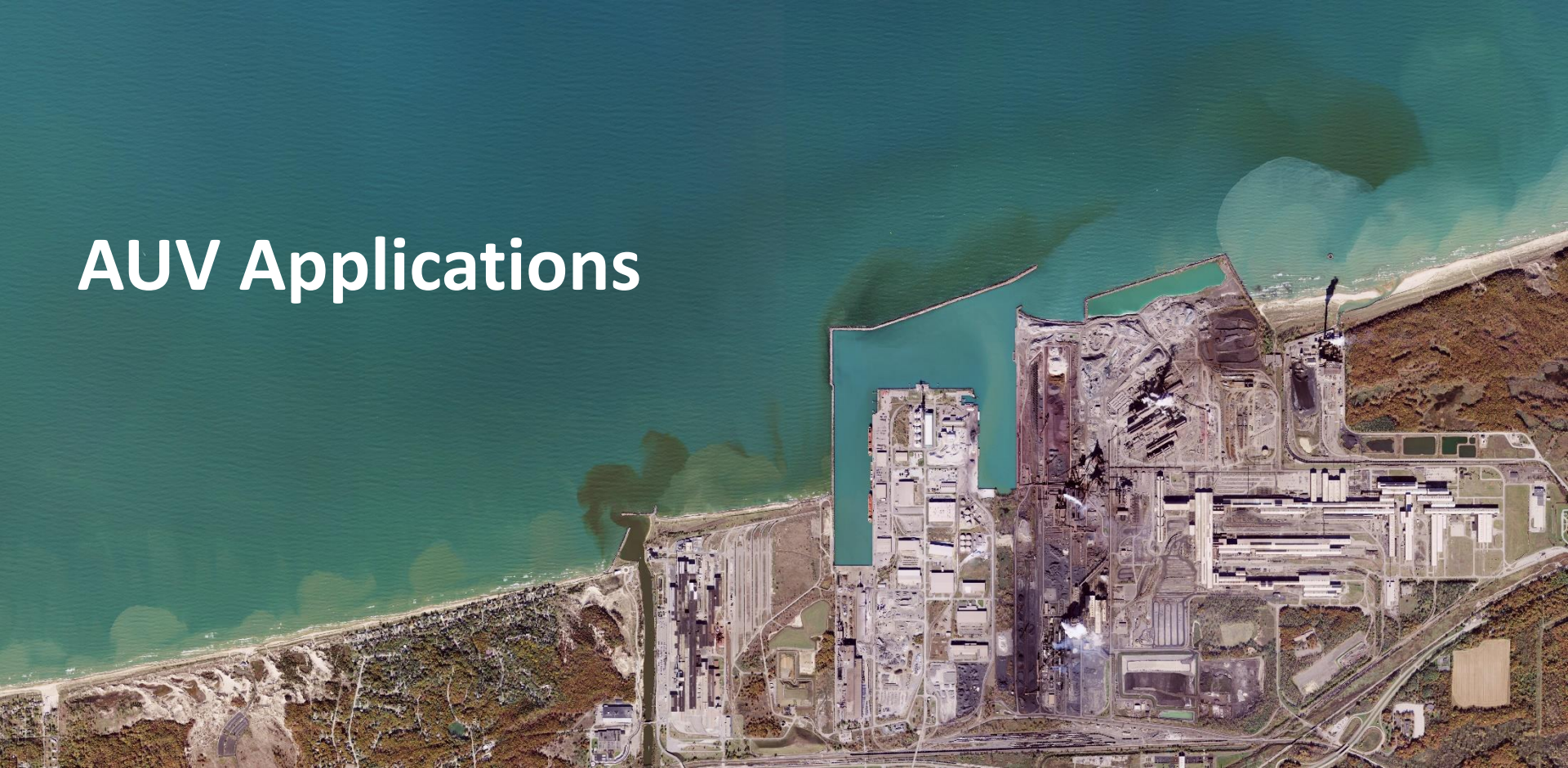
Benefits

- Extremely high resolution bathymetric data
- Accurate means of determining reservoir capacity
- Repeat surveys can reveal variations over time
- Inspection/identification of submerged objects without divers
- Newer systems are compact and can be deployed from “vessels of opportunity”

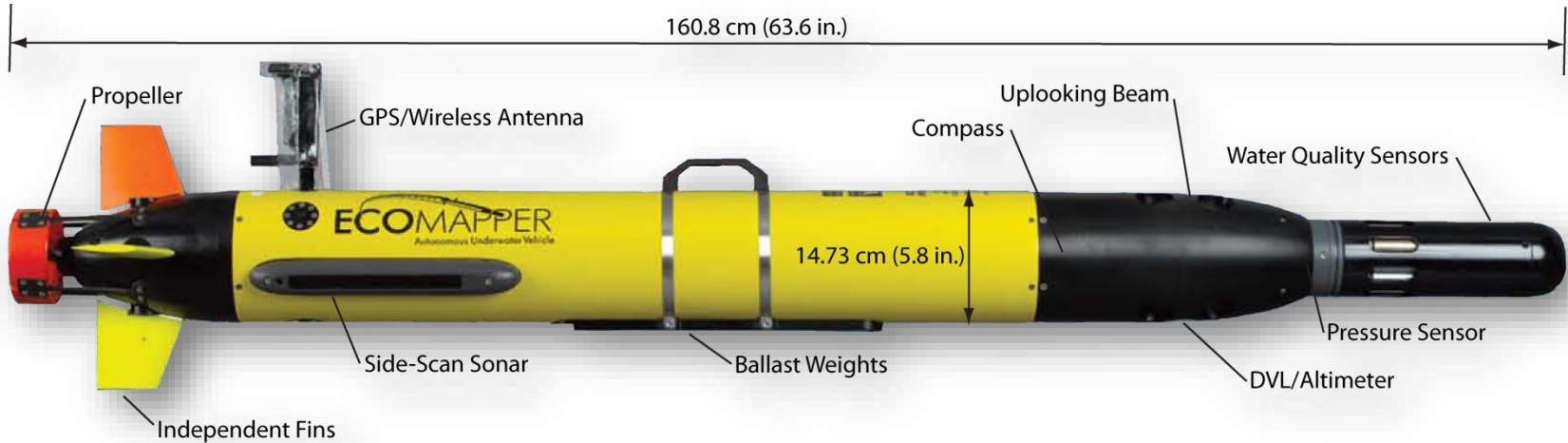
Limitations

- minimum of 3 feet of depth
- up to 900 feet of depth (for our systems)
- processing time (1 day survey ~ 1 week processing)
- more components = more things that can go wrong in the field (newer systems are a significant improvement)

AUV Applications



AUV applications



What kind of data?

- Bathymetric mapping
- Side-scan sonar imagery
- Water quality mapping
- Pressure sensors for depth
- GPS
- Integrated and geospatially referenced

Autonomous

- Hazardous conditions
- 24/7
- Saves man-hours

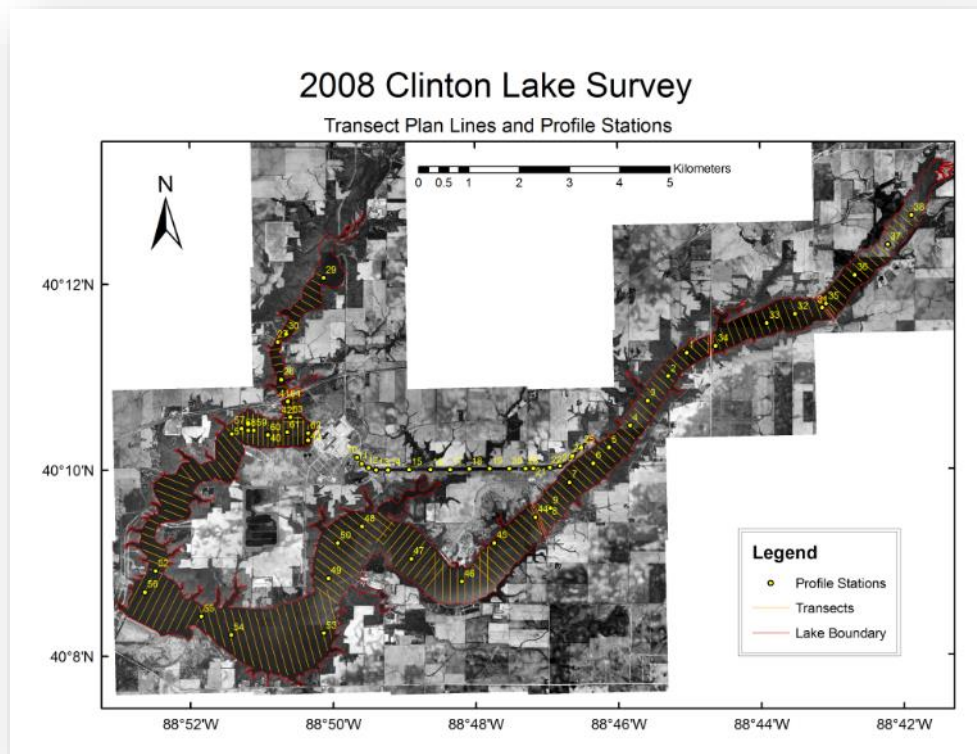
AUV applications – Data density

Spatially and temporally dense data

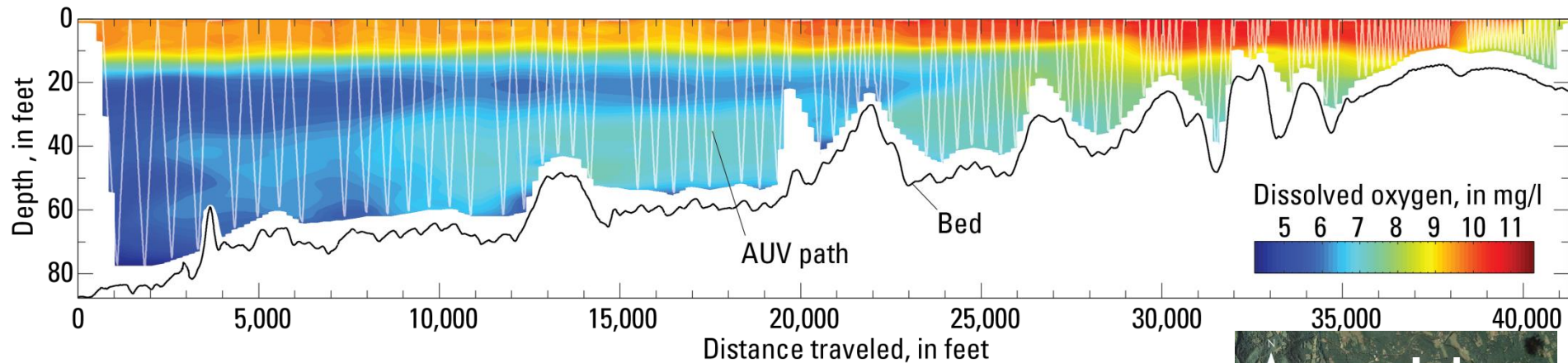
- AUVs generally collect data at high rates (generally at least 1 hz)
- Survey missions can span 10's of miles and produce hundreds of thousands of data points

Example: Clinton Lake (IL)

- 5,000 acre reservoir
- 228 transects in 55 hours
- Over 190,000 data points
- 108 miles covered by AUV



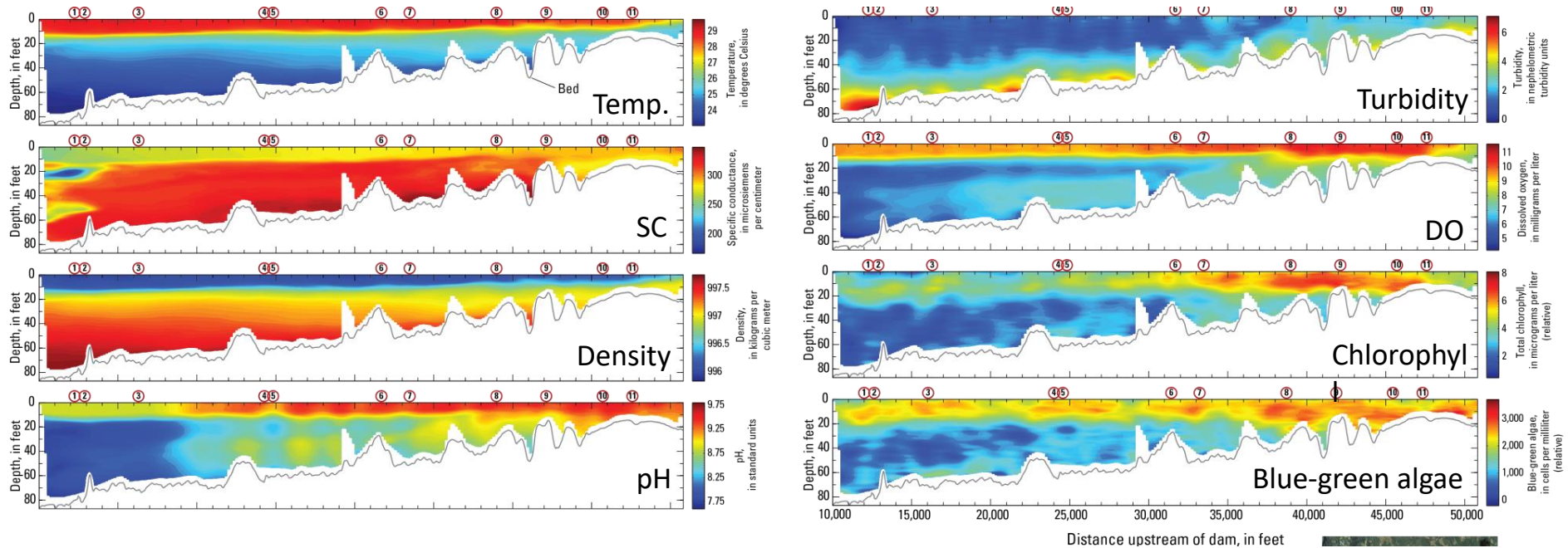
AUV applications – Data density



- 7.8-mile longitudinal transect
- 224 profiles of the water column
- 3.5 hours to complete
- 12,000 data points

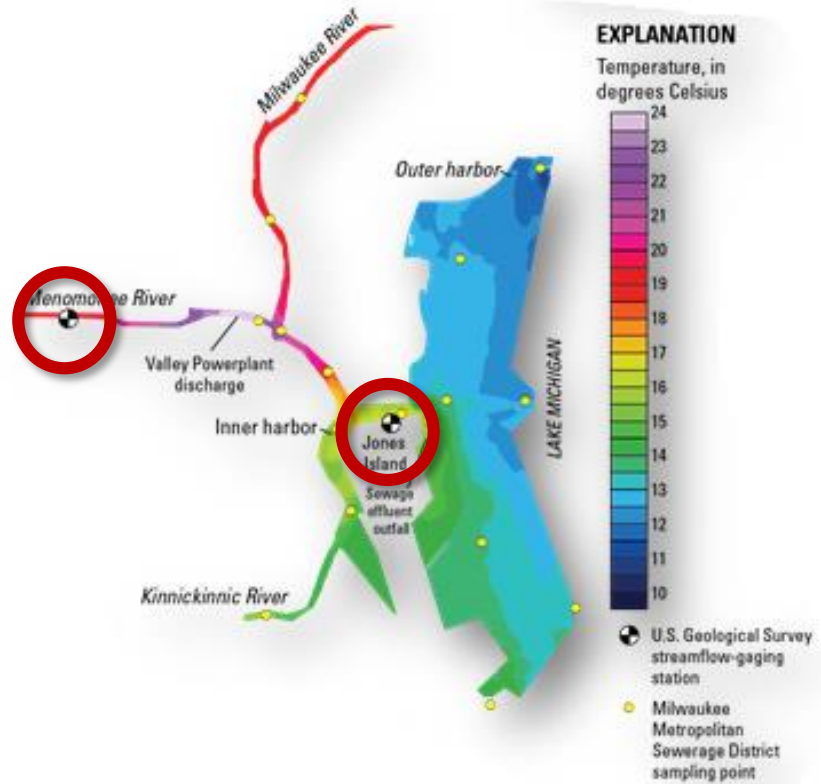


AUV applications – One survey, multiple parameters



Lake Lillinonah

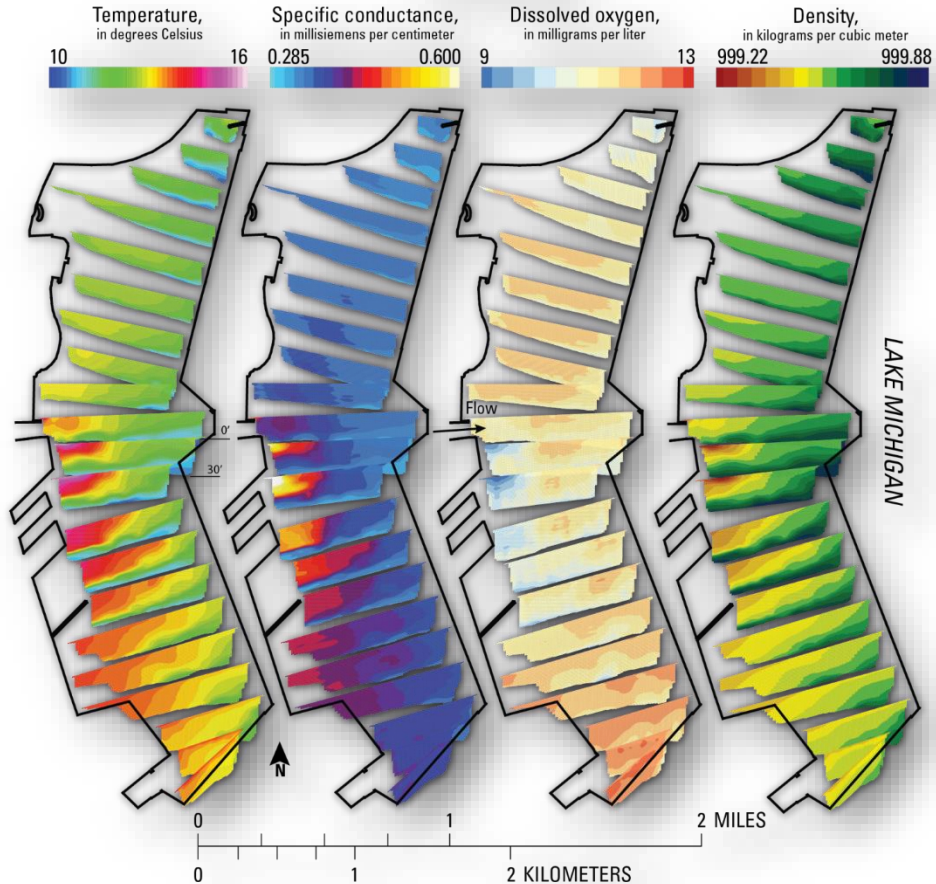
AUV applications – Fills the gap between gages



Milwaukee Harbor
***NMN Lake Michigan Pilot Project**

AUV applications – Mapping in 3D

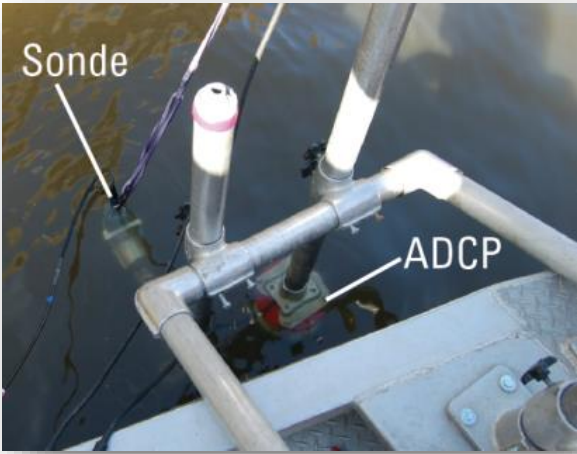
EXPLANATION



Milwaukee Harbor
***NMN Lake Michigan Pilot Project**

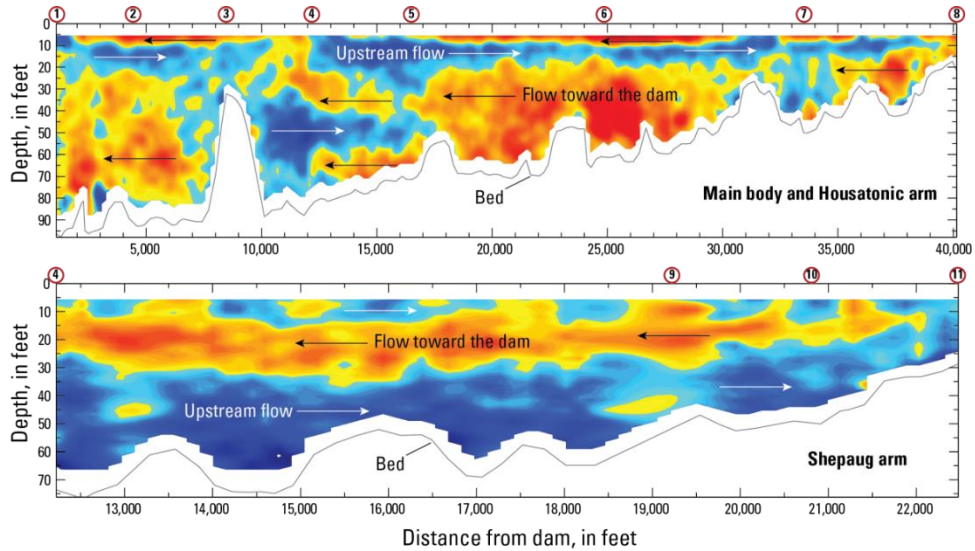
Combined AUV & Manned-boat surveys

Velocity data (ADCP)
Surface water quality
High-res bathymetry (MBES)



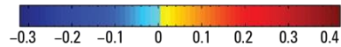
Combined AUV & Manned-boat surveys

Lake Lillinonah

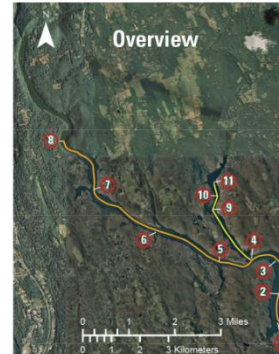


EXPLANATION

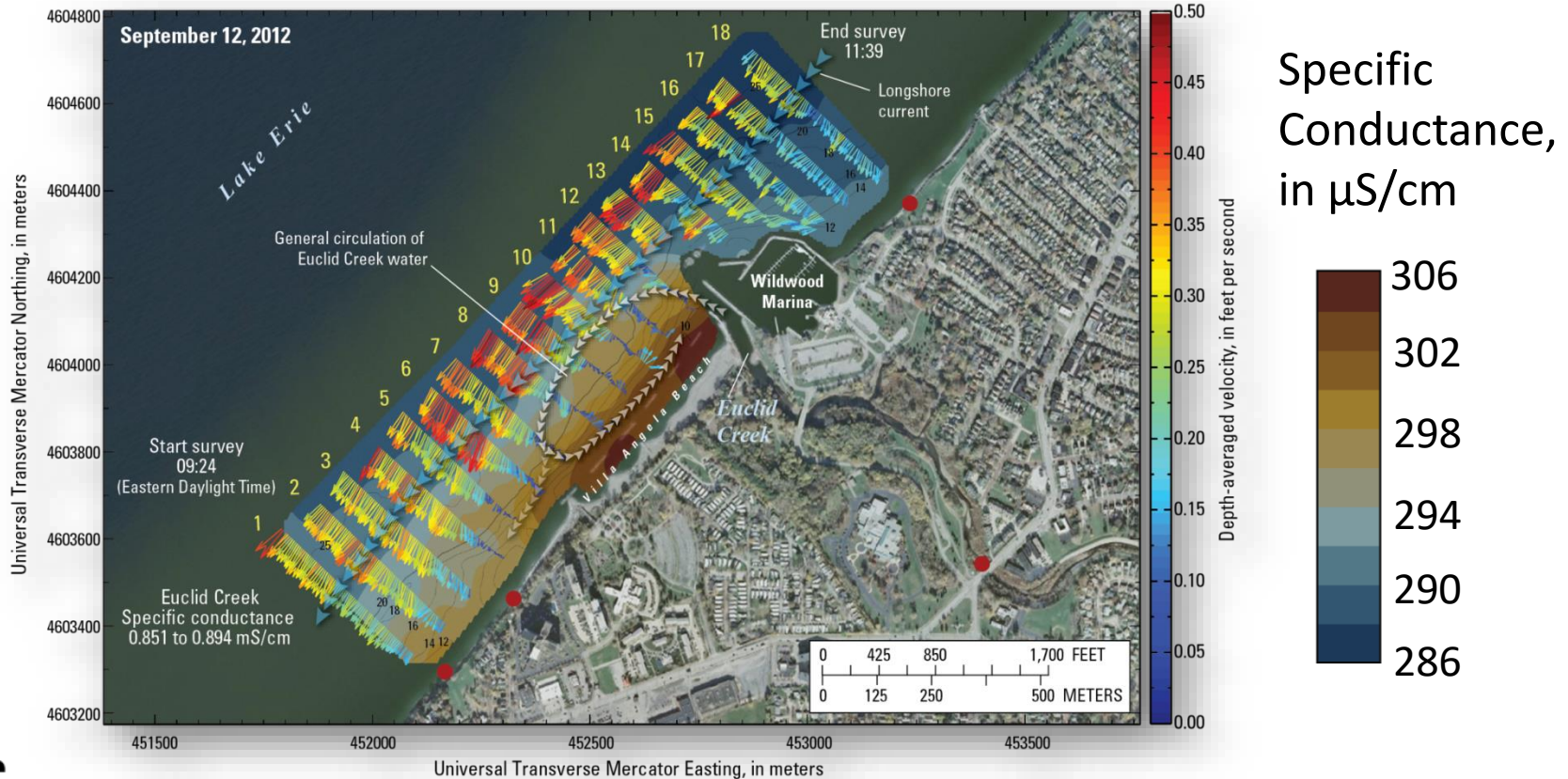
Streamwise velocity, in feet per second



- | | |
|---------------------------|--------------------------|
| ① Begin main profile | ⑦ Cove |
| ② End oxygen diffusers | ⑧ End of main profile |
| ③ Shelf on inside of bend | ⑨ Shepaug bend 2 |
| ④ Confluence | ⑩ Shepaug bend 1 |
| ⑤ Newtown Cove | ⑪ End of Shepaug profile |
| ⑥ Route 133 bridge | |



Combined AUV & Manned-boat surveys



AUV Tradeoffs

Benefits

- Highly efficient
- Repeat surveys show changes in time
 - Useful for evaluating restoration efforts
- Dense integrated data “connects the dots” and can reveal underlying processes
- Can help guide future sampling strategies
- A tool for rapid response to emergencies (spills, flooding etc.)

Limitations

- High cost, high risk
- Accurate underwater navigation is not easy
- Sensor payloads are limited
- Poor performance in areas with strong currents
- Processing time

Point Locations

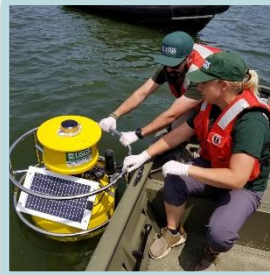


Profiles/Samples

Point locations
Snapshot(s) in time

Buoys and gages

Point locations
Continuous in time



Mapping



Moving-boat

Spatially dense
Snapshot(s) in time

AUV survey

Spatially dense
Snapshot(s) in time



What can a map reveal about your site?



Profiles/Samples

Moving-boat

Buoys and gages

AUV